

# Matt MacLeod

📍 Victoria BC, Canada | 📞 (250) 812-1936 | ✉️ mattmacleod12@gmail.com | [in matt-macleod](#) | [mattjmacleod.com](#)

## SUMMARY

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Ambitious Embedded Systems Engineer with 5 years' experience writing code and over 3+ years of professional experience contributing to all aspects of product development across a wide range of industries. Professionally, I've worked on many different projects with teams of varying sizes. Currently, I'm working as a Firmware Engineer at AMD where I have had the opportunity to contribute to the LPDDR5, DDR5 memory programs. As such, I am intimately familiar with contributing to a codebase in a team setting and comfortable with collaboration flows such as: pull requests, code reviews, automated pipelines, code formatters/linters and QA testing.

## SKILLS

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**Languages & Protocols:** C, C++, Python, CMake, Bash, git, perforce

**Embedded Systems:** Microprocessors: (Armv8-M, Armv7E-M, Avr), RTOS: (Zephyr, FreeRTOS), Interfaces: (SPI, I2C, UART, CAN)

**Hardware:** Design Software (Eagle, Altium, LTspice, Verdi, systemC), Debug Tools: (gdb, RTT)

**Lab Equipment:** Oscilloscope, Logic analyzer, Digital Multimeter, Signal Generator, Power Supplies

## WORK EXPERIENCE

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### Senior Firmware Engineer

MAY 2023 – PRESENT (11 Mo)

#### AMD

Vancouver, BC, Canada

- Wrote RISC-V based firmware solutions (in C) for DDR5/LPDDR5 PHY.
- Implemented features (using system C) from JEDEC specifications into an architectural model emulating DDR5/LPDDR5 PHY to expedite pre-silicon firmware development.
- Developed tools (using C++ 20) for emulating intrinsic analog characteristics of PHY to DRAM boundary to enhance training firmware accuracy.

### Embedded Firmware Engineer

JULY 2021 – APR (1Y, 9MO)

#### Rainhouse

Victoria, BC, Canada

- **Lead electronics team** in start-up (team of 4), to deliver all required hardware, embedded firmware, and full stack software for a wireless IoT, SMART CNC machine tool product line. Resulted in successful delivery of TRL-7 prototype, SDK, and the filing of 2 international patents.
- Wrote optimized, **multi-threaded embedded software (in C)** for 2 dual core **ARM SoCs**, to facilitate the real-time transmission and reception of 7 independent sensors over Bluetooth low energy at 1Mbps throughput.
- Experience with full board bring up of embedded ARM SoC including PCB design, bootloader configuration, debugging hardware peripherals and writing embedded software.
- Wrote the full stack IoT architecture encompassing gRPC streams to achieve 99.99% signal transmission over upper limit of Bluetooth low energy.
- Wrote **embedded Linux**, Zephyr **RTOS** based drivers (in **C**) for the nrf5340 ARM SoC to interface accelerometer ICs, ADC controller ICs, PCM microphones, thermocouples, and force sensors for high performance data collection.

### Electrical Systems Design Engineer (Internship)

JAN 2020 – AUG 2020 (8 MO)

#### Motorola Solutions

Vancouver, BC, Canada

- Developed a software for hardware, automation framework (using C++/python) to characterize the IO performance of SSDs, HDDs and raid controllers over a temperature hysteresis profile. Final solution resulted in a **12x faster test procedure** and improved the storage device characterization **accuracy by 50%**.
- Spearheaded the board bring up, **hardware re-design** (using Altium) and **debug** of a PoE controller board for an NVR product family. Resulted in successful delivery of first-generation rugged NVR product line.

### Electrical Engineer (Internship)

MAY 2019 – AUG 2019 (4 MO)

#### Seaspan ULC

Vancouver, BC, Canada

- **Collaborated across multi-disciplinary teams** and managed sub-contractors to deliver electrical single line diagrams for Canadian Coast Guard and Naval vessels.
- Sourced several major electrical instruments that became standard among a replenishment ship for the Canadian Navy.

## Jr Autonomous Systems Engineer (Internship)

SEPT 2018 – DEC 2018 (4 MO)

### InDro Robotics

Ganges, BC, Canada

- Designed, built and tested a working TRL-7 prototype of an after-market payload deployment mechanism that could be actuated through the DJI hand controller and mounts externally onto DJI's M210 drone. Resulted in the solution becoming a part of the company's product line.
- Programmed **embedded Linux flight controllers using C++** to integrate third party sensors and cameras with OEM drones for remote sensing operations.

## Electrical Engineer (Internship)

JAN 2018 – APR 2018 (4 MO)

### AML Oceanographic

Sidney, BC, Canada

- Tasked with using limited resources to improve the existing quality control process of PCBs before the next stage of manufacturing
- Automated the testing procedure of raw circuit boards using a combination of custom PCBs, test jigs and firmware validation scripts to yield a 5x faster quality control process.

## PERSONAL PROJECTS

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### Nissan Leaf Battery Analytics Framework (RP2040, C++, python)

- Goal: Decode the CanBus messages to persist intrinsic battery pack sensors from a depleted Nissan leaf pack to a cloud storage system for predictive analytics in a remote, off grid storage system.
- Embedded Systems: See custom [can bus decoding library](#)

### AI Home Security Guard (Raspberry Pi Zero W, C++):

- Goal: Create a device that utilizes facial and voice recognition methods to unlock door based on person's identity
- Hardware: Raspberry Pi Camera, USB Microphone, Bluetooth intercom System, Metal Gear Servo driven actuator to unlock door
- Embedded Systems: OpenCV Eigenfaces method for facial recognition, Voice to speech recognition algorithm used for user interface.

More Coming soon. For now, check out my [GitHub!](#)

## PATENTS

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- Sensor-based Smart Tooling for Machining Process Online Measurement and Monitoring ([Available](#))
- Real-Time DAS and SDK for Machine Parameter Online Measurement and Monitoring ([Available](#))

## EDUCATION

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Bachelor of Electrical Engineering (Digital and Embedded Systems Specialization)

SEPT 2016 – AUG 2021

University of Victoria

Victoria, BC, Canada